

Risking Other People's Money: Gambling, Limited Liability, and Optimal Incentives

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Abstract

We consider optimal incentive contracts when managers can, in addition to shirking or diverting funds, increase short term profits by putting the firm at risk of a low probability "disaster." To avoid such risk-taking, investors must cede additional rents to the manager. In a dynamic context, however, because managerial rents must be reduced following poor performance to prevent shirking, poorly performing managers will take on disaster risk even under an optimal contract. This risk taking can be mitigated if disaster states can be identified ex-post by paying the manager a large bonus if the firm survives. But even in this case, if performance is sufficiently weak the manager will forfeit eligibility for a bonus, and again take on disaster risk. Our model can explain why suboptimal risk-taking can emerge even when investors are fully rational and managers are compensated optimally.

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1 Introduction

Investors who entrust their funds to financial institutions such as investment banks, pension and hedge funds typically have little knowledge and/or understanding about how those institutions operate. In particular, it is extremely hard for investors to observe true realized cash flows of the financial institutions as well as correctly evaluate their risk exposure. This asymmetric information creates an opportunity for managers of the financial institutions to enrich themselves at the expense of the investors, which is aided by their ability to swiftly alter risk profiles of the assets under management. To protect their interest, the investors can try to write a contract with a manager of a financial institution that would align manager's objectives with theirs. The goal of this paper is to consider optimal incentive contracts in a setting in which a manager with limited liability privately chooses the riskiness of the project *and* can privately divert cash flows for her own consumption.

In particular, we consider a stylized model with two-dimensional moral hazard problem. To gain some basic economic insights we start with a one-period version of the model which we later extend to the infinite horizon using continuous time contracting framework. A risk neutral agent (manager) with limited liability runs a project which cash flows depend on its riskiness. The agent can choose between a low-risk and high-risk projects. Compared to the low-risk project, the high-risk project increases the probability of a high cash flow realization, but it also results in high losses in a bad state of nature, which we call “disaster.” The possibility of losses in the “disaster” state is eliminated when the low-risk project is chosen. We assume that the low-risk project is the first best. In addition to risk-taking, the agent can also manipulate the cash flows by diverting cash flows for her consumption. Neither the riskiness of the project nor the cash flow realizations are observed by the investors either ex-ante or ex-post unless the “disaster” state occurs.

The analysis of the one-period model generates a number of key insights. First, we find that although it is possible to write a contract that provides the agents with incentives to choose the low-risk project and not to steal the cash flows, it may be too expensive for the investors to break even. This is the case when the contract terms depend only on cash flows reported by the agent and when the probability of the “disaster” state is low. The economic intuition behind this result is pretty transparent. Any incentive compatible contract must reward the agent for reporting the high cash flow, otherwise the agent would steal it. However, conditioning agent's

reward on the reported cash flow also creates an incentive for the agent to take the high-risk project. The reason for that is that the agent benefits from the high cash flow and is protected from the losses by the limited liability in the “disaster” state. The contract that induces the agent to choose the low-risk project without stealing cash flows requires very high payoffs for the agent for the non-disaster outcomes. It is so because the agent with limited liability would otherwise ignore the disaster state, which occurs with a low probability, in her calculations of her expected payoff.

Our second finding is that the contract can be much less expensive for the investor to implement if the agent's payoff can be made conditional directly on the disaster state. In the optimal contract the agent receives a big bonus if the project does not generate a big loss in the “disaster” state. This is a cheaper way to provide incentives for the agent to choose the low-risk project, because the high levels of compensation in non-disaster states, which are much more likely to occur than the disaster state, are no longer required. We suggest that in practice this contract can be implemented by giving the manager out-of-the-money put options on the companies that are likely to be ruined in the disaster state, with a caveat that the manager can collect the payoff from the options only if her company remains in a good shape.

In our continuous time setting, the agent can increase the drift of the cash flow which is driven by Brownian motion, while creating a possibility of disaster, which we model as a Poisson process. Risk-taking occurs when the agent's continuation payoff is below a threshold, which is inversely proportional to the intensity of disaster arrival. Because managerial rents must be reduced following poor performance to prevent fund diversion, poorly performing agents will take on disaster risk even under an optimal contract. Unlike the static model, risk-taking can still happen even when disaster states are contractible. If performance is sufficiently weak the agent will forfeit eligibility for a bonus, and again take on disaster risk.

Compared to the setting with the one-dimensional moral hazard problem of DeMarzo and Sannikov (2006), the optimal contract has increased reliance on deferred compensation and provision of financial slack.

Another difference from DeMarzo and Sannikov (2006) is that public randomization can sometimes improve the contract. When the agent's continuation payoff drops to the threshold, below which the agent starts gambling, a small reduction in performance could lead to “harsh” punishments. On the other hand, a small improvement in performance in the gambling region

could lead to a big increase in the agent's continuation payoff, so that the agent stops gambling immediately.

Our paper bridges two strands of literature: the literature on moral hazard and/or hidden action and the literature on risk-taking. The vast literature on moral hazard (see Salanie (1997) for a survey of static models) has focused mostly on the problem of a principal who wants to induce an agent to exert the “optimal” effort. We build on a hidden action setting similar to the one used by DeMarzo and Sannikov (2006) in continuous time and DeMarzo and Fishman (2007a,b) in discrete time.

The risk-shifting was first introduced by Jensen and Meckling (1976) as an agency conflict between equity and debt holders of a levered firm. The agency problem is that the equity would gain all the upside of increasing the risk of the firm's assets-in-place, whereas debt would be responsible for its downside. Recognizing the importance of this agency problem, a large literature studies the impact of non-concave portions (such as puts and calls) of common executive compensations schemes on the risk-shifting incentives of managers who have access to dynamically complete markets. Contributions include Carpenter (2000), Ross (2004), and Basak, Pavlova, and Shapiro (2007). This literature treats the optimal contract as being exogenous.

The most closely related papers to the static version of our model are Diamond (1998), Palomino and Prat (2003), Hellwig (1994), and Biais and Casamatta (1999). Like us, they study a hidden-action moral hazard problem in which the agent controls both effort and the distribution of the outcome. Diamond (1998) and Palomino and Prat (2003) use delegated portfolio management as the economic motivation. Diamond (1989) asks whether, as the cost of effort shrinks relative to the payoffs, the optimal contract converges to the linear contract. He shows that if the agent has several ways to manipulate the outcome, the principal should offer the simplest possible compensation scheme, that is, the linear contract. While Diamond (1998) considers only three possible outcomes, Palomino and Prat (2003) allow for a continuum of outcomes. Similar to our setting, the agent in their model has limited liability and can sabotage (misreport) the realized return. They show that the optimal contract is simply a bonus contract - the agent is paid a fixed sum if the portfolio return is above a threshold. Also, by using an explicit parameterization of risk, they are able to analyze the sign of inefficiencies in risk taking. Hellwig (1994) and Biais and Casamatta (1999) are interested in the optimal financing of investment projects when managers must exert unobservable effort and can also switch to less

profitable riskier ventures. Both papers find that under some technical conditions optimal financial contracts can be implemented by a combination of debt and equity.

The most closely related papers to the dynamic version of our model are by Ou-Yang (2003) and Cadenillas, Cvitanic, and Zapatero (2007). Both papers are executed in a continuous time setting where agent controls both the drift (effort choice) and the volatility (project selection) of the underlying payoff process. Unlike us, neither paper allows for the limited liability of the agent. In addition, we allow for the endogenous liquidation before the terminal date of the project. This assumption is critical since it facilitates “all-or-nothing” strategy from the agent. Implementing this assumption in the economic setting of these two papers is technically infeasible since it would superimpose an optimal stopping problem over their current optimization routine. Finally, Makarov and Plantin (2010) develop a dynamic model of active portfolio management in which fund managers may secretly gamble in order to manipulate their reputation and attract more funds. They solve for the optimal contracts that deter this behavior and show that if investors are short-lived, then the manager must leave rents to investors in order to credibly commit not to gamble. If investors are long-lived, any contract that increases but defers expected bonuses after an outstanding performance is optimal. Contrary to our paper, Makarov and Plantin (2010) consider only observable actions by the agent.

The rest of the paper is organized as follows. Static model is presented in Section 2. The continuous time model is discussed in Section 3. Section 4 concludes.

2 One Period Model

2.1 Formulation

There are two risk-neutral players. First, the principal (investor(s)), owns the company which has value of its assets-in-place equal to L .¹ The principal can add a new project to the company in which case he has to hire the second player, the agent, to run it. The cash flows from the project, $Y(q)$, depend on the degree of its riskiness, $q \in \{0,1\}$, which is controlled by the agent. The project has three possible cash-flow realizations

¹ L can be viewed as a liquidation value of the firm.

$$Y(q) = \begin{cases} 1, & \text{with probability } p^0 + qp^1 \\ 0, & \text{with probability } 1 - p^0 - q(p^1 + p^2). \\ -M, & \text{with probability } qp^2 \end{cases} \quad (1)$$

The choice of $q = 0$ corresponds to the “safe” project, in which case only nonnegative cash flows 0 and 1 are possible and its expected value is equal to p^0 . The choice of $q = 1$ corresponds to the “risky” project. In this case the probability of the highest cash flow, 1, is increased by p^1 , but a new negative cash flow $-M$ can be realized with probability $p^2 < p^1$. We assume that the “safe” project has higher expected cash flows than the “risky” project

$$p^1 - p^2M < 0. \quad (2)$$

L can be interpreted as the direct loss from the operations and it could be quite large, but not greater than the value of assets-in-place, i.e. $M < L$. Under this assumption the principal has limited liability with respect to the company, but not the new project.

The agent can take two actions both unobservable by the principle. First, the agent upon privately observing that the realized cash flow is equal to 1 can report to the principal that the cash flow is 0. By doing so the agent receives a private benefit of $\lambda \in [0,1]$. We interpret diversion of the firm's cash flows as stealing. We assume that the agent can secretly transfer money from the firm's account to his own account using accounting manipulations. However, other hidden activities that benefit the agent at the expense of the principal may fit the setting of the model as well. For instance, the agent can inefficiently use the firm's cash flows in order to receive non-pecuniary benefits. The fraction $1 - \lambda$ represents the cost of diversion, which can be attributed to different kinds of expenses and inefficiencies associated with the diversion.

Such hidden action setting allows for one-to-one mapping into the hidden effort setting. In this setting the agent chooses a binary effort $e \in \{0,1\}$ at a cost of λe . Here $e=1$ stands for “high” (optimal) effort, while $e=0$ stands for “low” (inferior) effort. The payoffs conditional on the joint choice of effort and risk are given by

$$Y(q, e) = \begin{cases} 1, & \text{with probability } e(p^0 + qp^1) \\ 0, & \text{with probability } 1 - e(p^0 + qp^1) - qp^2. \\ -M, & \text{with probability } qp^2 \end{cases} \quad (3)$$

Under the hidden effort interpretation the incentive compatibility constraint enforces the optimal effort.

Privately choosing the “riskiness” of the project, q , is the second action the agent can take. We also assume that the agent has limited liability. We interpret limited liability as a disallowance of positive transfers from the agent to the principle, i.e. the agent cannot be legally forced to pay back the principal.

The principal does not observe neither the realized cash flow, y , nor the riskiness, q , implemented by the agent and therefore he must rely wholly on the agent to report the cash flow realizations, y . We assume that the monitoring is prohibitively costly. Under these assumptions neither y nor q is contractable.

If the principal agrees to initiate the project, at the time of initiation the principal and the agent sign a contract that governs their relationship over the life of the project. The contract obligates the agent to report realizations of the cash flows to the principal. Without loss of generality, we assume that the contract requires the agent to pay the reported cash flows to the principal immediately. The contract also specifies transfer payment from the principal to the agent, $a^d(\hat{y}) \geq 0$, which depends on the reported cash flow.

Next we solve for the optimal contract for three different cases: (i) low risk taking when contracting on the states of nature is impossible; (ii) high risk taking; and (iii) low risk taking when contracting on the states of nature is possible.

2.2 Optimal contract implementing the safe project

Here we derive optimal incentive compatible contract that enforces the safe project choice. A contract is *optimal* if it maximizes the principal's payoff, $b(a; q)$, subject to a certain payoff a for the agent.

DEFINITION 1: *We say that the incentive compatible contract enforcing safe project choice $\phi = \{a^d(0), a^d(1), a^d(-M)\}$ that implements payoffs a and $b(a|\phi)$ for the agent and the principal, respectively, is optimal if there is no other incentive compatible contract $\hat{\phi}$ with the same payoff for the agent a , but with a higher payoff for the principal, $b(a|\hat{\phi}) > b(a|\phi)$.*

This definition is based on the time-zero expected payoffs. The principal's income at the end of the period is given by the difference between the reported cash flow $\hat{y}$, transfer $a^d(\hat{y})$ and the value of assets-in-place L . Therefore the principal's problem is to choose a contract $\phi = \{a^d(0), a^d(1), a^d(-M)\}$ that maximizes his expected payoff, $b(a; q = 0)$:

$$b(a; 0) = \max_{a^d(\cdot) \geq 0} E[Y - a^d(\hat{y}) + L | q = 0], \quad (4)$$

subject to the promise-keeping (PK thereafter) constraint

$$(PK): a = E[a^d(\hat{y}) | q = 0], \quad (5)$$

the incentive compatibility (IC thereafter) constraint

$$(IC): a^d(1) \geq a^d(0) + \lambda, \quad (6)$$

and the low-risk-taking (LRT thereafter) constraint

$$(LRT): E[a^d(Y(q=0))] \geq E[a^d(Y(q=1))], \quad (7)$$

The function $b(a; 0)$ represents the highest possible payoff attainable by the principal, given any arbitrary payoff a to the agent when the safe project is implemented. The PK constraint implies that the agent's expected payoff is a . The IC constraint ensures that when the cash flow of 1 is realized the agent truthfully reports it. The LRT constraint guarantees that the agent selects safe project over the risky project. Therefore, it is obvious that $a^d(-M) = 0$ which we are going to use throughout this subsection.

Solving for the contracting problem means finding the optimal *non-negative* transfers $\{a^d(0), a^d(1)\}$. Our solution method relies on the work of DeMarzo and Fishman (2007a, b). In the case of the low risk taking the optimization problem (4) can be written as

$$b(a; 0) = \max_{a^d(\cdot) \geq 0} p^0(1 + A - a^d(1)) + (1 - p^0)(0 + L - a^d(0)), \quad (8)$$

$$\text{s.t. (PK): } a = p^0 a^d(1) + (1 - p^0) a^d(0), \quad (9)$$

$$(IC): a^d(1) \geq a^d(0) + \lambda, \quad (10)$$

$$(LRT): (p^1 + p^2) a^d(0) \geq p^1 a^d(1), \quad (11)$$

In rewriting the LRT constraint we have used that

$$E[a^d(\hat{y}) | q] = (p^0 + qp^1) a^d(1) + (1 - p^0 - q(p^1 + p^2)) a^d(0). \quad (12)$$

Figure 1 illustrates constraints (9) to (11) in the $(a^d(0), a^d(1))$ plane. The forty-five degree line starting at λ represents the IC constraint. It is binding along the line and is slack above it. The second straight line that starts at zero represents LRT constraint. It binds along the line and is slack below it. Therefore, the set of all possible transfers which jointly satisfies IC and LRT lies in a wedge between these two lines. The thick dot shows the point of intersect between the two lines. The coordinates of these points can be found as follows. Combining (10) and (11) we obtain

$$0 \geq p^1 \underbrace{(a^d(1) - a^d(0))}_{\geq \lambda} - p^2 a^d(0) \geq p^1 \lambda - p^2 a^d(0). \quad (13)$$

It implies that constraints (9) and (11) can be jointly satisfied when

$$a^d(0) \geq \frac{p^1}{p^2} \lambda. \quad (14)$$

When used as equality it yields the horizontal coordinate of the intersection point. The vertical coordinate of the intersection point, $a^d(1) = (\frac{p^1}{p^2} + 1)\lambda$, is immediately obtained by substituting (14) into the IC constraint. The dotted line shows the PK constraint. When PK constraint passes through the intersection point the promised utility a is equal to $\bar{a}$

$$p^0 \underbrace{(\frac{p^1}{p^2} + 1)\lambda}_{a^d(1)} + (1 - p^0) \underbrace{\frac{p^1}{p^2} \lambda}_{a^d(0)} = \bar{a}, \quad (15)$$

from where the cutoff $\bar{a}$ is equal to

$$\bar{a} = \frac{p^1 + p^2 p^0}{p^2} \lambda. \quad (16)$$

For values of a greater-or-equal to $\bar{a}$, the PK constraint passes through at least one point in the area where both IC and LRT are jointly satisfied. Formally, it can be written as:

$$a \geq p^0 (a^d(0) + \lambda) + (1 - p^0) a^d(0) = a^d(0) + p^0 \lambda \geq \bar{a}. \quad (17)$$

The intersect point is, however, the “cheapest” contract to the principal. Therefore, the IC binds and the cheapest transfers to the agent are equal to $\left(\frac{p^1}{p^2}\lambda, \left(1 + \frac{p^1}{p^2}\right)\lambda\right)$. Finally, we can substitute the PK constraint (9) into the objective function (8) to obtain

$$\begin{aligned} b(a;0) &= \max_{\{a^d(1), a^d(0)\}} L + p^0 - \underbrace{\left(p^0 a^d(1) + (1-p^0)a^d(0)\right)}_a \\ &= L + p^0 - a. \end{aligned} \tag{18}$$

Combining (17) and (18) and taking into account that payoffs to the principal are infeasible if the condition (17) is violated yields the complete solution for the second period principal's continuation payoff, $b(a;0)$, which is summarized by the Proposition 1.

PROPOSITION 1: *The optimal incentive compatible contract implementing safe project is $\phi = \{a^d(0) = a - p^0\lambda, a^d(1) = a + (1-p^0)\lambda, a^d(-M) = 0\} \forall a \geq \bar{a}$. The principal's optimal continuation payoff under ϕ is given by*

$$b(a;0) = \begin{cases} L + p^0 - a, & a \geq \bar{a} \\ -\infty, & 0 \leq a < \bar{a} \end{cases}, \tag{19}$$

where the minimum expected payoff to the agent $\bar{a}$ is equal to

$$\bar{a} = \frac{p^1 + p^2 p^0}{p^2} \lambda.$$

The highest payoff to the principal is achieved at $a = \bar{a}$. We use the notation $-\infty$ to indicate that for values of $a < \bar{a}$ there exists no incentive compatible contract implementing safe project. Since p^2 can be arbitrarily small (but not necessarily the expected losses since M can be made arbitrarily large), the optimal contract can become too expensive for the principal to implement. This happens since in order to jointly satisfy IC and LRT constraints the agent has to be given high payoffs when cash flows are either 0 or 1. Figure 2 also helps to understand the comparative statics of the optimal contract. As λ increases, the intersection point shifts in the north-east direction, which means that higher transfers to the agents are needed to prevent his misbehavior. When probability of the losses falls, agent has more incentive to gamble and once again the intersection point shifts in the north-east direction.

2.3 Optimal contract implementing the risky project

Here we derive optimal incentive compatible contract that does not enforce the safe project choice.

DEFINITION 2: We say that the incentive compatible contract $\phi = \{a^d(0), a^d(1), a^d(-M)\}$ that implements payoffs a and $b(a|\phi)$ for the agent and the principal, respectively, is optimal if there is no other incentive compatible contract $\hat{\phi}$ with the same payoff for the agent a , but with a higher payoff for the principal, $b(a|\hat{\phi}) > b(a|\phi)$.

Just like in the case when only the safe project was implemented, the principal's income at the end of the period is given by the difference between the reported cash flow $\hat{y}$, transfer $a^d(\hat{y})$ and the value of assets-in-place L . However, in contrast with the previous case, risky project can end either in success, in which case the continuation payoff to the principal is equal to $y + L - a^d$ for any promised payoff to the agent, a^d , or in failure, in which case the continuation payoff to the principal is equal to $L - M$. It is obvious again that the optimal contract should have $a^d(-M) = 0$. The principal's problem is to choose a contract $\phi = \{a^d(0), a^d(1), a^d(-M)\}$ that maximizes his expected payoff, $b(a; q = 1)$:

$$b(a; 1) = \max_{a^d(\cdot) \geq 0} E \left[Y - a^d(\hat{y}) + L \mid q = 1 \right], \quad (20)$$

subject to the PK and IC constraints

$$(PK): a = E \left[a^d(\hat{y}) \mid q = 1 \right], \quad (21)$$

and

$$(IC): a^d(1) \geq a^d(0) + \lambda.$$

The problem (20) can be rewritten as

$$b(a; 1) = \max_{a^d(\cdot) \geq 0} \bar{p} (1 + L - a^d(1)) + (1 - \bar{p} - p^2) (L - a^d(0)) + p^2 (L - M) \quad (22)$$

$$\text{s.t. (PK): } a = \bar{p} a^d(1) + (1 - \bar{p} - p^2) a^d(0), \quad (IC): (10) \quad (23)$$

where we have denoted $\bar{p} \equiv p^0 + p^1$.

Figure 2 illustrates constraints (23) in the $(a^d(0), a^d(1))$ plane. Once again, the forty-five degree line that starts at λ represents the IC constraint. It is binding along the line and is slack above it. The dotted line shows the PK constraint. It is immediate to realize that the cheapest contract to the principle is given by $\{a^d(0) = 0, a^d(1) = \lambda\}$.

Finally, combining (10) and PK from (23) we obtain the low bound on the promised utility, a :

$$a \geq \bar{p}(a^d(0) + \lambda) + (1 - \bar{p} - p^2)a^d(0) = a^d(0) + \bar{p}\lambda \geq \bar{p}\lambda. \quad (24)$$

≥ 0

Now we can substitute the PK constraint (23) into the objective function (22) and take into account that payoffs to the principal are infeasible when $a \leq \bar{p}\lambda$ yields the complete solution for the second period principal's continuation payoff, $b(a;1)$, summarized by Proposition 2.

PROPOSITION 2: *The optimal incentive compatible contract implementing risky project is $\phi = \{a^d(0) = a - \bar{p}\lambda, a^d(1) = a + (1 - \bar{p})\lambda, a^d(-M) = 0\} \forall a \geq \bar{p}\lambda$. The principal's payoff under ϕ is given by*

$$b(a;1) = \begin{cases} \bar{p} + L - p^2M - a, & a \geq \bar{p}\lambda \\ -\infty, & 0 \leq a < \bar{p}\lambda \end{cases} \quad (25)$$

Corollaries 1 and 2 highlight our next set of results.

COROLLARY 1: *The lowest agent's compensation under the incentive compatible contract implementing risky project, $\bar{p}\lambda$, is smaller than the lowest compensation under incentive compatible contract implementing safe project, $\bar{a}$, i.e. $\bar{p}\lambda < \bar{a}$.*

This result follows immediately from the definition of $\bar{a}$. The optimal incentive compatible contract allowing for the risky project is less expensive than the optimal incentive compatible contract that disallows the risky project because it does not require high levels of the agent's compensation when cash flows are either equal to 0 or 1. At the same time, this contract can result in large losses to the principal.

COROLLARY 2: *When the agent's compensations under the incentive compatible contracts with and without risk taking are equal to their lowest values, the principle is better off allowing risk-taking if*

$$p^2 L - p^1 < \frac{1-p^2}{p^2} p^1 \lambda. \quad (26)$$

This inequality can be satisfied even when the expected losses, $p^2 L$, are high. Note that the right hand side of the inequality (26) goes to infinity when p^2 goes to zero, while M can be made large enough so that the expected losses remain significant. Therefore, while the safe project is strictly better than the risky project, the principal would prefer the risky project or no project at all to the safe project when the loss probability p^2 is low even though the expected losses could be substantial.

2.4 Contracting on the states of nature

In this subsection we allow the principle to contract not only on the reported cash flows, but also on the states of nature. Consider the following incomplete information game between the principal and the agent. At time zero nature makes a draw: With probability p^2 it draws a “disaster” state, and it draws “good” state with probability $1-p^2$. Ex ante, neither principal nor agent know the exact state of nature, but ex post the true state of nature is a public knowledge. In the “good” state the payoffs conditional on the risk strategy, $q \in \{0,1\}$, are as follows

$$Y_G(q) = \begin{cases} 1, & \text{with probability } g^0 + qg^1 \\ 0, & \text{with probability } 1 - g^0 - qg^1, \\ -M, & \text{with probability } 0 \end{cases} \quad (27)$$

while in the “disaster” state the payoffs are

$$Y_D(q) = \begin{cases} 1, & \text{with probability } 0 \\ 0, & \text{with probability } 1 - q. \\ -M, & \text{with probability } q \end{cases} \quad (28)$$

This game can be easily mapped onto the original game by matching the probabilities of payoff of 1:

$$(1 - p^2)(g^0 + qg^1) = p^0 + qp^1, \quad (29)$$

and 0:

$$p^2(1 - q) + (1 - p^2)(1 - g^0 - qg^1) = 1 - p^0 - q(p^1 + p^2). \quad (30)$$

The probability of the disaster payoff $-M$ is matched by construction. We can use either one of these equations to get g^0 and g^1 in terms of p^0 , p^1 , and p^2 . Setting $q = 0$ in (29) yields

$$g^0 = \frac{p^0}{1 - p^2} = 1 - \frac{p^1}{1 - p^2} \leq 1, \quad (31)$$

and setting $q = 1$ in (29) yields

$$g^1 = \frac{p^1}{1 - p^2} = 1 - \frac{p^0}{1 - p^2} \leq 1. \quad (32)$$

Therefore, there exists a non-trivial match between probabilities.

We now write the optimal low-risk incentive compatible contract based on this game. The crucial difference in this case is that the transfer to the agent, $a^d(\hat{y}, n)$, is not a function of just the reported cash flow, $\hat{y}$, but also depends on the state of nature, $n \in \{G, D\}$. The definition of the optimal incentive compatible contract that enforces the safe project choice is given below. The notion of optimality remains unchanged from previous subsections.

DEFINITION 3: *We say that the incentive compatible contract enforcing safe project choice $\phi = \{a^d(0, G), a^d(1, G), a^d(0, D), a^d(-M, D)\}$ that implements payoffs a and $b(a|\phi)$ for the agent and the principal, respectively, is optimal if there is no other incentive compatible contract $\hat{\phi}$ with the same payoff for the agent a , but with a higher payoff for the principal, $b(a|\hat{\phi}) > b(a|\phi)$.*

The principal's problem is to choose a contract

$$\phi = \{a^d(0, G), a^d(1, G), a^d(0, D), a^d(-M, D)\}, \quad (33)$$

that maximizes his expected payoff, $b(a; q = 0)$:

$$b(a; 0) = \max_{a^d(\cdot) \geq 0} E^{n,Y} [Y - a^d(\hat{y}, n) + L | q = 0], \quad (34)$$

subject to the PK constraint

$$(PK): a = E^{n,Y} [a^d(\hat{y}, n) | q = 0], \quad (35)$$

the IC constraint

$$(IC): a^d(1, G) \geq a^d(0, G) + \lambda, \quad (36)$$

and the LRT constraint

$$(LRT): E^{n,Y} [a^d(Y_n(q=0), n)] \geq E^{n,Y} [a^d(Y_n(q=1), n)], \quad (37)$$

where $E^{n,Y}[\cdot]$ denotes expectations over the states of nature and payoffs.

The problem of the principal can be written as

$$b(a; 0) = \max_{a^d(\cdot) \geq 0} p^0 (1 + L - a^d(1, G)) + (1 - p^0 - p^2) (0 + L - a^d(0, G)) + p^2 (L - a^d(0, D)), \quad (38)$$

$$\text{s.t. (PK): } a = p^0 a^d(1, G) + (1 - p^0 - p^2) a^d(0, G) + p^2 a(0, D), \text{ (IC): (36)} \quad (39)$$

$$\begin{aligned} (LRT): p^0 a^d(1, G) + (1 - p^0 - p^2) a^d(0, G) + p^2 a^d(0, D) \geq \\ (p^0 + p^1) a^d(1, G) + (1 - p^0 - p^1 - p^2) a^d(0, G). \end{aligned} \quad (40)$$

The LRT constraint can be simplified to:

$$(LRT): p^2 a^d(0, D) \geq p^1 (a^d(1, G) - a^d(0, G)). \quad (41)$$

Here we have already converted probabilities $g^{0,1}$ into the original probabilities $p^{0,1}$ using relations (31) and (32). Under this specification, the principal's objective function (38) is fully consistent with the program (8) where the conditioning on the states of nature is not allowed. The unconditional probability of cash flow 1 is equal to p^0 and the unconditional probability of cash flow 0 is equal to $1 - p^0$. The key difference between two specifications is that cash flow 0 occurs with probability $1 - p^0 - p^2$ in the “good” state of nature, and with probability p^2 in the “disaster” state when the safe project is implemented.

The immediate observation we can make is that $a^d(-M, D) = 0$. Figure 3 provides graphical exposition of the solution to the rest of this contracting problem. It shows the set of optimal transfers to the agent in the $(a^d(0, G), a^d(1, G))$ plane. The first forty-five degree line that starts at λ represents the IC constraint. It is binding along the line and it is slack above it.

The second forty-five degree line that starts at $\frac{p^2}{p^1} a^d(0, D)$ represents the LRT constraint. The LRT constraint is slack below this line and binds along it. Both constraints are satisfied as long as $\frac{p^2}{p^1} a^d(0, D) \geq \lambda$, with the minimum payoff to the agent achieved when this constraint binds to yield

$$a^d(0, D) = \frac{p^1}{p^2} \lambda. \quad (42)$$

In this case the optimal choice of $(a^d(0, G), a^d(1, G))$ satisfying PK constraint is $(0, \lambda)$, meaning that the PK constraint passes through $(0, \lambda)$ point on the plot. This is the cheapest transfer which satisfies all three constraints. The principal receives

$$\begin{aligned} b(a; 0) &= \max_{\{a^d(0), a^d(1)\}} p^0 + L - \underbrace{(p^0 a^d(1, G) + (1 - p^0 - p^2) a^d(0, G) + p^2 a^d(0, D))}_a \\ &= p^0 + L - a, \end{aligned} \quad (43)$$

when

$$a \geq p^0 (a^d(0, G) + \lambda) + (1 - p^0 - p^2) a^d(0, G) + p^1 \lambda \geq \bar{p} \lambda, \quad (44)$$

where we have introduced $\bar{p} \equiv p^0 + p^1$. Proposition 3 summarizes our results.

PROPOSITION 3: *Conditional on the state of nature optimal incentive compatible contract implementing safe project is*

$$\phi = \left\{ a^d(0, G) = a - \bar{p} \lambda, a^d(1, G) = a - \bar{p} \lambda + \lambda, a^d(0, D) = a - \bar{p} \lambda + \frac{p^1}{p^2} \lambda, a^d(-M, D) = 0 \right\} \forall a \geq \bar{p} \lambda.$$

The principal's payoff under ϕ is given by

$$b(a; 0) = \begin{cases} L + p^0 - a, & a \geq \bar{p} \lambda \\ -\infty, & 0 \leq a < \bar{p} \lambda \end{cases}. \quad (45)$$

The minimum expected payoff to the agent, $(p^0 + p^1) \lambda$, is smaller than $\bar{a}$, and it is much smaller than $\bar{a}$ when p^2 is small. It makes this contract cheaper for the principal to implement. In fact,

the cost of implementing this contract to the principal is the same as are the cost of the contract implementing risky project.

The intuition behind this result is transparent and as follows. Depending on the state of nature, cash flow 0 can be either bad or good outcome -- it is bad in the “good” state and good in the “disaster” state. When contracting on the states of nature is not allowed as in Propositions 1, the agent has to be given high rewards for both 0 and 1 cash flows in order to implement the safe project, which makes the optimal contract expensive. When contracting on the states of nature is allowed, the contract can differentiate between cash flows 0 and 1, and, therefore, it is not necessary to promise the agent high payoffs for either cash flow in the good state of nature.

Instead, it is optimal to give the agent high payoff $a^d(0, D) = a - \bar{p}\lambda + \frac{p^1}{p^2}\lambda$ for cash flow 0 in the disaster state of nature. While this payoff can become unbounded when p^2 goes to zero, the expected payoff, $p^2 a^d(0, D)$, remains finite.

2.5 Implementation

In practice, conditioning on states of nature while possible is quite challenging. It is so because states of nature are difficult to categories and verify. However, our optimal contract requires conditioning only on the “extreme” states of nature, such as the current financial crisis. During this crisis a number of major financial institutions either went bankrupt or their equity suffered extreme losses. Therefore, one practical way to implement our contract is as follows. At the time when the whole economy is doing well, managers who have either authority or ability to change the riskiness of their projects should be awarded out-of-money put options. These options should be written on the companies in the same line of business which would be ruined in the case of disaster. This implementation is relatively inexpensive at the award time since these options would be cheap. However they would result in large payoffs to their holders in the case of the disaster. The necessary caveat is that the manager would get this payoff only if his company stays afloat (payoff 0 in the “disaster” state in our model). Manager would rationally anticipate this large reward at the outset and would implement the safe project.

These contracts are, however, not observed in practice. One argument against compensation like that is that it provides managers with extra incentives to take down their

competitors. Our paper is the first to point out the particular benefits of using put options on other companies as a part of managerial compensations. In light of the recent financial crisis, the benefits of such compensation can outweigh its downside, since losses from excessive risk-taking it helps to prevent can be quite large. A comprehensive cost-benefit analysis of such executive compensation should be executed in a general equilibrium setting which is beyond the scope of this paper and is left for future research.

3 Continuous Time Model

3.1 Formulation

This section extends the one-period model to the continuous time, infinite horizon setting. The agent manages a project that generates a continuous cash flow stream, Y_t , that depends on the riskiness of the project, $q_t \in \{0,1\}$, as follows

$$dY_t = (\mu_0 + \mu_1 q_t)dt + \sigma dZ_t - Mq_t dN_t, \quad (46)$$

where Z_t is a standard Brownian motion, and σ is the volatility of cash flow process. The drift of the cash flow process is μ_0 in the “low” risk regime, $q_t = 0$, and is increased by $\mu_1 > 0$ in the “high” risk regime, $q_t = 1$. In addition, the high risk regime exposes the project to a possibility of a “disaster” outcome, in which case the project generates a one-time large loss $M > 0$ and gets liquidated immediately. “Disaster” process N is a standard Poisson process with intensity δ that describes arrivals of “disasters”, $dN_t = 1$. A disaster results in a “disaster outcome” for the project, i.e., loss of M , only if the project was in the high risk regime at the moment when the disaster arrived.

We consider a two dimensional agency problem both stemming from hidden actions taken by the agent. The first dimension is that the riskiness of project can be privately changed by the agent at any time and is not observable or verifiable by the investors, (except the times when a disaster takes place). We assume that $\mu_1 < \delta M$, i.e., switching to the high risk regime leads to lower cash flows in expectation.

The second dimension is that the agent observes the realized cash flows Y , but the principal does not. The agent reports cash flows $\{\hat{Y}_t; t \geq 0\}$ to the principal, where the difference between Y and $\hat{Y}$ is determined by the agent’s hidden actions. The principal receives only the reported cash flows $d\hat{Y}_t$ from the agent.

The contract specifies compensation for the agent dI_t , as well as a termination times τ_L and τ_D , that are based on the agent's reports and disaster realizations. We begin our analysis assuming that the contract cannot be made conditional on the occurrence of the disaster, unless the disaster outcome occurs, in which case the project is terminated at time

$$\tau_D \equiv \inf \{t : dN_t = 1 \& q_t = 1\}. \quad (47)$$

Thus, the termination time τ_L and agent's compensation, dI_t , depend only on the history of the agent's reports.

In this section we model the agency problem by allowing the agent to divert cash flows for his own private benefit. The agent receives a fraction $\lambda \in (0,1]$ of the cash flows he diverts; if $\lambda < 1$, there are dead-weight costs of concealing and diverting funds. The agent can also exaggerate cash flows by putting his own money back into the project. By altering the cash flow process in this way, the agent receives a total flow of income of

$$[dY_t - d\hat{Y}_t]^\lambda + dI_t, \text{ where } [dY_t - d\hat{Y}_t]^\lambda \equiv \underbrace{\lambda(dY_t - d\hat{Y}_t)^+}_{\text{diversion}} - \underbrace{(dY_t - d\hat{Y}_t)^-}_{\text{over-reporting}}. \quad (48)$$

The agent is risk neutral and discounts his consumption at rate γ . The agent maintains a private savings account, from which he consumes and into which he deposits his income. The principal cannot observe the balance of the agent's savings account. The agent's balance S_t grows at interest rate $\rho < \gamma$.

$$dS_t = \rho S_t dt + [dY_t - d\hat{Y}_t]^\lambda + dI_t - dC_t, \quad (49)$$

where $dC_t \geq 0$ is the agent's consumption at time t . The agent must maintain a nonnegative balance on his account, that is, $S_t \geq 0$.

Once the contract is terminated, the agent receives payoff of zero. Therefore, the agent's total expected payoff from the contract at date zero is given by⁸

$$W_0 = E \left[\int_0^\tau e^{-\gamma s} dC_s \right], \quad (50)$$

where $\tau \equiv \min\{\tau_L, \tau_D\}$.

The principal discounts cash flows at rate r , such that $\gamma > r \geq \rho$.⁹ Once the contract is terminated, she receives expected liquidation payoff $L \geq 0$ unless the termination was caused by the "disaster" outcome, in which case the liquidation value of the project is $L - M$. The principal's total expected profit at date zero is then

$$b_0 = E \left[\int_0^\tau e^{-rs} (d\hat{Y}_s - dI_s) + e^{-r\tau} \left(L1_{\tau_L < \tau_D} + (L - M)1_{\tau_D \leq \tau_L} \right) \right]. \quad (51)$$

The project requires the start-up external capital of $K \geq 0$. The principal offers to contribute this capital in exchange for a contract $\{\tau_L, I\}$ that specifies a termination time $\tau_L \wedge \tau_D$ and payments $\{I_t; 0 \leq t \leq \tau_L \wedge \tau_D\}$ that are based on reports $\hat{Y}$. Formally, I is a $\hat{Y}$ -measurable continuous process, and τ_L is a $\hat{Y}$ -measurable stopping time.

In response to a contract $\{\tau_L, I\}$, the agent chooses a feasible strategy to maximize his expected payoff. A *feasible* strategy is a triple of processes $\{q, C, \hat{Y}\}$ adapted to Y such that

- (i) $q \in \{0, 1\}$,
- (ii) $\hat{Y}$ is continuous and, if $\lambda < 1$, $Y_t - \hat{Y}_t$ has bounded variation,¹⁰
- (iii) C_t is non-decreasing, and
- (iv) the savings process, defined by (2), stays nonnegative.

The agent's strategy $\{q, C, \hat{Y}\}$ is incentive compatible if it maximizes his total expected payoff W_0 given a contract (τ_L, I) . An *incentive compatible contract* refers to a quintuple $\{\tau_L, I, q, C, \hat{Y}\}$ that includes the agent's recommended strategies.

The optimal contracting problem is to find an incentive compatible contract $\{\tau_L, I, q, C, \hat{Y}\}$ that maximizes the principal's profit subject to delivering the agent an initial required payoff W_0 . By varying W_0 we can use this solution to consider different divisions of bargaining power between the agent and the principal. For example, if the agent enjoys all the bargaining power due to competition between principals, then the agent must receive the maximal value of W_0 subject to the constraint that the principal's profit be at least zero.

3.2 Derivation of the Optimal Contract

We solve the problem of finding an optimal contract in three steps. First, we show that it is sufficient to look for an optimal contract within a smaller class of contracts, namely, contracts in which the agent chooses to report cash flows truthfully and maintain zero savings. Second, we consider a relaxed problem by ignoring the possibility that the agent can save secretly. Third, we show that the contract is fully incentive compatible even when the agent can save secretly.

We begin with a revelation principle type of result:¹¹

LEMMA A: *There exists an optimal contract in which the agent (i) chooses to tell the truth, and (ii) maintains zero savings.*

The intuition for this result is straightforward – it is inefficient for the agent to conceal and divert cash flows ($\lambda \leq 1$) or to save them ($\rho \leq r$), as we could improve the contract by having the principal save and make direct payments to the agent. Thus, we will look for an optimal contract in which truth telling and zero savings are incentive compatible.

3.2.1. The Optimal Contract with Non-Contractible Disaster Process

Note that if the agent could not save, then he would not be able to over-report cash flows and he would consume all income as it is received. Thus,

$$dC_t = dI_t + \lambda(dY_t - d\hat{Y}_t). \quad (52)$$

We relax the problem by restricting the agent's savings so that (52) holds and allowing the agent to steal only at a bounded rate.¹² After we find an optimal contract for the relaxed problem, we show that it remains incentive compatible even if the agent can save secretly or steal at an unbounded rate.

One challenge when working in a dynamic setting is the complexity of the contract space. Here, the contract can depend on the entire path of reported cash flows $\hat{Y}$. This makes it difficult to evaluate the agent's incentives in a tractable way. Thus, our first task is to find a convenient representation of the agent's incentives. Define the agent's promised value $W_t(\hat{Y}, q)$ after a history of reports $(\hat{Y}_s, 0 \leq s \leq t)$ to be the total expected payoff the agent receives, from transfers and termination utility, if he tells the truth and chooses risk q after time t :

$$W_t(\hat{Y}, q) = E_t \left[\int_t^\tau e^{-\gamma(s-t)} dC_s \right]. \quad (53)$$

The following result provides a useful representation of $W_t(\hat{Y}, q)$.

LEMMA B: *At any moment of time $t \leq \tau$, there is a sensitivity $\beta_t(\hat{Y}, q)$ of the agent's continuation value towards his report and public randomization process $R_t(\hat{Y}, q)$ such that*

$$dW_t = (\gamma + \delta q_t)W_t dt - dI_t + \beta_t(\hat{Y}, q)(d\hat{Y}_t - (\mu_0 + \mu_1 q_t)dt) - q_t W_t dN_t + (dR_t(\hat{Y}, q) - E[dR_t(\hat{Y}, q)]). \quad (54)$$

This sensitivity $\beta_t(\hat{Y}, q)$ is determined by the agent's past reports $\hat{Y}_s$, and riskiness of the project $q_s, 0 \leq s \leq t$.

Proof of Lemma B: See Appendix.

Informally, the agent has incentives not to steal cash flows if he gets at least λ of promised value for each reported dollar, that is, if $\beta_t \geq \lambda$. If this condition holds for all t then the agent's payoff will always integrate to less than his promised value if he deviates. If this condition fails on a set of positive measure, the agent can obtain at least a little bit more than his promised value if he underreports cash when $\beta_t < \lambda$.

In addition, the agent has incentives to switch to the high-risk regime to increase the project cash flows. However, this can lead to a disaster outcome resulting in the loss of continuation payoff for the agent. Intuitively, the agent would be willing to take on more risk only if his continuation payoff is below a certain threshold. Indeed, if the agent decides to switch to the high-risk regime at time t , the cash flow will be increased by $\mu_1 dt$. If the agent truthfully reports the cash flow and switches back to low-risk regime at time $t+dt$, it results in an increase of the agent's continuation payoff by $\beta_t \mu_1 dt$. However, with probability δdt this could lead to a disaster outcome between time t and $t+dt$, and the loss of continuation payoff W_t . Thus, choosing the high-risk regime is incentive compatible if and only if $\beta_t \mu_1 dt > \delta W_t dt$, or $W_t < \beta_t \frac{\mu_1}{\delta}$.

LEMMA C: *If the agent cannot save, truth-telling is incentive compatible if and only if $\beta_t \geq \lambda$ for all $t < \tau$. Moreover, if $\beta_t \geq \lambda$, it is optimal for the agent to choose the low-risk regime whenever $W_t \geq \beta_t \frac{\mu_1}{\delta}$ and switch to the high-risk regime whenever $W_t < \beta_t \frac{\mu_1}{\delta}$.*

Proof of Lemma C: See Appendix.

Now we use the dynamic programming approach to determine the most profitable way for the principal to deliver the agent any value W . Here we present an informal argument, which we formalize in the proof of Proposition 1 in the Appendix. Denote by $b(W)$ the principal's value function (the highest profit to the principal that can be obtained from a contract that provides the agent the payoff W).

Because the principal has the option to provide the agent with W by paying a lump-sum transfer of $dI > 0$ and moving to the optimal contract with payoff $W - dI$,

$$b(W) \geq b(W - dI) - dI. \quad (55)$$

Equation (55) implies that $b'(W) \geq -1$ for all W ; that is, the marginal cost of compensating the agent can never exceed the cost of an immediate transfer. Define W^C as the lowest value such that $b'(W^C) = -1$. Then it is optimal to pay the agent according to

$$dI = \max(W - W^C, 0). \quad (56)$$

These transfers, and the option to terminate, keep the agent's promised value between 0 and W^C . Within this range, Lemmas B and C imply that the agent's promised value evolves according to

$$dW_t = (\gamma + \delta q_t)W_t dt + \beta_t \sigma dZ_t - q_t W_t dN_t + (dR_t - E[dR_t]), \quad (57)$$

when the agent is telling the truth. We need to determine the sensitivity β of the agent's value to reported cash flows and the randomization process R that maximize the principal's value.

Let $d\Delta_t^R$ denote the stochastic probability that the randomization process R results in a jump in the agent's continuation payoff between t and $t+dt$. Let J_t^R denote the size of this jump. Using Ito's lemma, the principal's expected cash flows and changes in contract value are given by

$$\begin{aligned} E[dY + db(W)] = & \left(\mu_0 + \mu_1 q + (\gamma + \delta q)Wb'(W) + \frac{1}{2}\beta^2\sigma^2b''(W) + \delta q(L - M - b(W)) \right) dt + \\ & E \left[\beta \sigma b'(W) dZ + (b(W + J^R) - b(W)) d\Delta^R - b'(W) J^R d\Delta^R \right]. \end{aligned} \quad (58)$$

Because at the optimum the principal should earn an instantaneous total return equal to the discount rate, r , we have the following equation for the value function:

$$\begin{aligned} rb(W)dt = & \max_{\beta, q, J^R, \Delta^R} \left(\mu_0 + \mu_1 q + (\gamma + \delta q)Wb'(W) + \frac{1}{2}\beta^2\sigma^2b''(W) + \delta q(L - M - b(W)) \right) dt + \\ & E \left[\beta \sigma b'(W) dZ + (b(W + J^R) - b(W) - b'(W)J^R) d\Delta^R \right] \end{aligned} \quad (59)$$

$$\text{s.t. } \beta \geq \lambda$$

$$q = 1 \Leftrightarrow \beta > \frac{\delta W}{\mu_1} \quad (60)$$

$$J^R \geq -W$$

$$d\Delta^R \geq 0$$

First we note that optimal randomization assures that function b is weakly concave. If $b(W)$ is convex around W , then it is optimal to randomize around W , since $(b(W + J^R) - b(W) - b'(W)J^R)$ is positive for some J^R . However, the randomization makes $b(W)$ affine in W , and hence $b''(W)=0$. Thus, $b(W)$ cannot be convex, and the last term in equation (59) is zero.

Equation (59) can be rewritten as follows:

$$rb(W) = \mu_0 + \gamma W b'(W) + \max_{\beta, q} \frac{1}{2} \beta^2 \sigma^2 b''(W) + q \delta \left(\left(\frac{\mu_1}{\delta} - M \right) + (L - (b(W) - W b'(W))) \right). \quad (61)$$

Given the concavity of b , $b''(W) \leq 0$ and $L - (b(W) - W b'(W)) \leq 0$. In addition, $\frac{\mu_1}{\delta} - M < 0$, because the high-risk project is dominated by the low risk project. As a result, the smallest possible β and q are optimal. Thus, $\beta = \lambda$, and $q=1$ for $W < W^S \equiv \lambda \frac{\mu_1}{\delta}$, and $q=0$ for $W > W^S$. Intuitively, since the inefficiency in this model results from early termination and gambling, choosing lowest possible β has a double benefit. First, reducing the risk to the agent lowers the probability that the agent's promised value falls to zero. Second, lower β reduces incentives for the agent to gamble.

We require three boundary conditions to pin down a solution to this equation and the boundary W^C . The first boundary condition arises because the principal must terminate the contract to hold the agent's value to 0, so $b(0) = L$. The second boundary condition is the usual "smooth pasting" condition – the first derivatives must agree at the boundary – and so $b'(W^C) = -1$.¹⁷ The final boundary condition is the "super contact" condition for the optimality of W^C , which requires that the second derivatives match at the boundary. The principal's value function therefore satisfies the following second-order ordinary differential equation:

$$rb(W) = \mu_0 + \gamma W b'(W) + \frac{1}{2} \lambda^2 \sigma^2 b''(W), \quad W^S \leq W \leq W^C, \quad (62)$$

with $b(W) = b(W^C) - (W - W^C)$ for $W > W^C$. This condition implies that $b''(W^C) = 0$, or equivalently, using equation (62),

$$rb(W^C) + \gamma W^C = \mu_0. \quad (63)$$

This boundary condition has a natural interpretation: It is beneficial to postpone payment to the agent by making W^C larger because doing so reduces the risk of early termination. Postponing payment is sensible until

the boundary (63), when the principal and agent's required expected returns exhaust the available expected cash flows.

The following proposition formalizes our findings:

PROPOSITION 5: *The contract that maximizes the principal's profit and delivers the value $W_0 \in [0, W^C]$ to the agent takes the following form: W_t evolves according to*

$$dW_t = (\gamma + \delta q_t)W_t dt - dI_t + \lambda(d\hat{Y}_t - (\mu_0 + \mu_1 q_t)dt) - q_t W_t dN_t - J(dK_t^S - \Lambda_t^S) + J(dK_t^P - \Lambda_t^P). \quad (64)$$

When $W_t \in [0, W^C)$, $dI_t = 0$. When $W_t = W^C$, payments dI_t cause W_t to reflect at W^C . If $W_0 > W^C$, an immediate payment $W_0 - W^C$ is made. The contract is immediately terminated when the disaster outcome occurs. The contract is also terminated when W_t reaches 0. Jumps of the size $J = W^S - W^P$ can happen when W_t reaches thresholds W^P or W^S . The cumulative intensities Λ_t^S and Λ_t^P of the jumps are given by

$$d\Lambda_t^S = -1_{\{W_t=W^S\}} \frac{\left[(\gamma + \delta)W_t dt + \lambda(d\hat{Y}_t - (\mu_0 + \mu_1)dt) \right]^-}{W^S - W^P}, \quad (65)$$

$$d\Lambda_t^P = 1_{\{W_t=W^P\}} \frac{\left[(\gamma + \delta)W_t dt + \lambda(d\hat{Y}_t - (\mu_0 + \mu_1)dt) \right]^+}{W^S - W^P}. \quad (66)$$

If $W_0 \in (W^P, W^S)$, the agent's time zero continuation payoff will be W^P with probability $\frac{W^S - W_0}{W^S - W^P}$, and W^S with probability $\frac{W_0 - W^P}{W^S - W^P}$, when the project is initiated. It is optimal for the agent to choose the high-risk regime whenever $W_t < W^S$ and the low-risk regime whenever $W_t \geq W^S$. The principal's expected payoff at any point is given by a weakly concave function $b(W_t)$, which satisfies

$$rb(W) = \mu_0 + \mu_1 + (\gamma + \delta)Wb'(W) + \frac{1}{2}\lambda^2\sigma^2b''(W) + \delta(L - M - b(W)), \quad (67)$$

on the interval $[W^0, W^P]$, and

$$rb(W) = \mu_0 + \gamma Wb'(W) + \frac{1}{2}\lambda^2\sigma^2b''(W), \quad (68)$$

on the interval $[W^S, W^C]$.

When

$$(r + \delta)b(W^S) - (\gamma + \delta)b'(W^S)W^S \leq \mu_0 + \mu_1 - \delta(M - L),$$

there are no jumps in the agent's continuation payoff, i.e., $W^P = W^S$ and the solutions of (67) and (68) are concave functions and their values and first derivatives agree at W^S .

When

$$(r + \delta)b(W^S) - (\gamma + \delta)b'(W^S)W^S > \mu_0 + \mu_1 - \delta(M - L),$$

$W^P < W^S$ and b is given by a continuously differentiable function, which is concave on $[W^0, W^P]$ and $[W^S, W^C]$, and is affine on (W^P, W^C) :

$$b(W) = b(W^P) + \frac{b(W^S) - b(W^P)}{W^S - W^P}(W - W^P), \quad (69)$$

where W^P solves

$$(r + \delta)b(W^P) - (\gamma + \delta)b'(W^P)W^P = \mu_0 + \mu_1 - \delta(M - L).$$

The additional boundary conditions are given by

$$b'(W) = -1 \text{ for } W \geq W^C, \quad (70)$$

$$rb(W^C) = \mu - \gamma W^C, \quad (71)$$

$$b(0) = L, \quad (72)$$

Proof of Proposition 5: See Appendix

3.2.1. The Optimal Contract with Contractible Disaster Process

In this section, we derive the optimal contract when the disaster process is observable and contractible. As before, when the disaster arrives and the risk is high, the disaster outcome occurs, resulting in immediate liquidation of the project and the negative payoff of $L - M$ to the investors. However, unlike the previous setting, the terms of the contract can be conditional on the event when the disaster arrives and the risk is low. We will call continuation payoff adjustments conditional on such an event “bonuses.”

It is straightforward to modify Lemma B for the setting with bonuses.

LEMMA D: *At any moment of time $t \leq \tau$, there is a sensitivity $\beta_t(\hat{Y}, q)$ of the agent's continuation value towards his report and a bonus process $B_t(\hat{Y}, q)$ such that*

$$dW_t = \left(\gamma W_t - \delta \left((1 - q_t) B_t(\hat{Y}, q) - q_t W_t \right) \right) dt - dI_t + \beta_t(\hat{Y}, q) (d\hat{Y}_t - (\mu_0 + \mu_1 q_t) dt) + \left((1 - q_t) B_t(\hat{Y}, q) - q_t W_t \right) dN_t. \quad (75)$$

This sensitivity $\beta_t(\hat{Y}, q)$ and the bonus process $B_t(\hat{Y}, q)$ are determined by the agent's past reports $\hat{Y}_s$, and riskiness of the project $q_s, 0 \leq s \leq t$.

The main difference from Lemma B is the jump B_t in the agents continuation payoff that happens when the disaster occurs and the risk is low. Unlike the jump in the agent's continuation payoff when the disaster outcome occurs, the size of bonus jump B_t is an endogenous variable. We could add an additional randomization term in (30) as we did in Lemma B. However, as we argue later, randomization would not improve the contract.

As before, the agent has no incentives to steal cash flows if he gets at least λ of promised value for each reported dollar, that is, if $\beta_t \geq \lambda$. This condition is not affected by the bonuses, which are conditional on the disaster process. However, the bonuses have a direct effect on the agent's incentives to gamble. In the high-risk regime, a disaster outcome results not only in the loss of the continuation payoff W_t for the agent, but also in the loss of the bonus B_t that the agent would get in the low-risk regime. On the other hand, the agent's benefits from switching to the high-risk regime are unaffected by the bonuses and are equal to an increase of the agent's continuation payoff by $\beta_t \mu_1 dt$ over the period between time t and $t+dt$. Thus, choosing the high-risk regime is incentive compatible if and only if $\beta_t \mu_1 dt > \delta(W_t + B_t)dt$, or $W_t + B_t < \beta_t \frac{\mu_1}{\delta}$. The following lemma summarizes our conclusions.

LEMMA E: *If the agent cannot save, truth-telling is incentive compatible if and only if $\beta_t \geq \lambda$ for all $t < \tau$. Moreover, if $\beta_t \geq \lambda$, it is optimal for the agent to choose the low-risk regime whenever $W_t + B_t \geq \beta_t \frac{\mu_1}{\delta}$ and switch to the high-risk regime whenever $W_t + B_t < \beta_t \frac{\mu_1}{\delta}$.*

Proof of Lemma E: See Appendix.

Lemma E states that positive bonuses conditional on the no-disaster outcome reduce the agent's incentive to choose the inefficient high-risk project. The minimum bonus needed to implement the low-risk regime is equal to $\min\{\beta_t \frac{\mu_1}{\delta} - W_t, 0\}$. Since the principal's expected payoff is a concave function of W_t , it is optimal to choose the smallest possible β and B that satisfy incentive compatibility and implement a desired level of risk. Thus, in the optimal contract, it should always be the case that $\beta_t = \lambda$. In addition, the optimal

bonus should be $B_t = \min\{W^S - W_t, 0\}$ when it is optimal to implement the low-risk regime and zero when the high-risk regime is optimal.

PROPOSITION 6: *The contract that maximizes the principal's profit and delivers the value $W_0 \in [0, W^1]$ to the agent is characterized by three regions:*

- a. *High-risk regime ($q_t=1$) without bonuses when $W_t \in [0, W^B)$*
- b. *Low-risk regime ($q_t=0$) with the bonus equal to $(W^S - W_t)$ when $W_t \in [W^B, W^S)$*
- c. *Low-risk regime ($q_t=0$) with no bonuses when $W_t \in [W^S, W^C]$*

The agent's continuation payoff W_t evolves according to

$$dW_t = \begin{cases} (\gamma + \delta)W_t dt + \lambda(d\hat{Y}_t - (\mu_0 + \mu_1)dt) - q_t W_t dN_t & \text{for } W_t \in [0, W^B) \\ (\gamma W_t - \delta(W^S - W_t))dt + \lambda(d\hat{Y}_t - \mu_0 dt) + ((1 - q_t)(W^S - W_t) - q_t W_t)dN_t & \text{for } W_t \in [W^B, W^S) \\ \gamma W_t dt - dI_t + \lambda(d\hat{Y}_t - \mu_0 dt) - q_t W_t dN_t & \text{for } W_t \in [W^S, W^C] \end{cases} \quad (76)$$

When $W_t \in [0, W^C)$, $dI_t = 0$. When $W_t = W^C$, payments dI_t cause W_t to reflect at W^C . If $W_0 > W^C$, an immediate payment $W_0 - W^C$ is made. The contract is terminated at time τ , when W_t reaches zero or the disaster outcome occurs. The principal's expected payoff at any point is given by a concave smooth function $b(W)$, which satisfies

$$rb(W) = \mu_0 + \mu_1 + (\gamma + \delta)Wb'(W) + \frac{1}{2}\lambda^2\sigma^2b''(W) + \delta(L - M - b(W)) \quad \text{for } W_t \in [0, W^B) \quad (77)$$

$$rb(W) = \mu_0 + (\gamma W - \delta(W^S - W))b'(W) + \frac{1}{2}\lambda^2\sigma^2b''(W) + \delta(b(W^S) - b(W)) \quad \text{for } W_t \in [W^B, W^S) \quad (78)$$

$$rb(W) = \mu_0 + \gamma Wb'(W) + \frac{1}{2}\lambda^2\sigma^2b''(W) \quad \text{for } W_t \in [W^S, W^C] \quad (79)$$

The principal's continuation function $b(W)$ also satisfies the following boundary conditions $b(0) = L$ and $rb(W^C) = \mu - \gamma W^C$. The consumption boundary is determined by $b'(W^C) = -1$, while the bonus region is determined by $W^S = \lambda \frac{\mu_1}{\delta}$ and W^B that solve

$$L + \frac{\mu_1}{\delta} + W^S b'(W^B) = M + b(W^S). \quad (80)$$

4 Empirical Implications [To be completed...]

Our model provides several key empirical insights.

- (i) Higher probability of the unobservable risk-taking is associated with a higher managerial compensation (total package). It can be interpreted, for instance, that executive compensation in industries with larger number of risky investment opportunities should be higher than in industries where risky investment opportunities are scarce.
- (ii) Risk-taking is likely to take place after a history of poor performance, when the agent has little “skin” left in the game.
- (iii) Conditional on the crisis occurring, the failure is less likely for institutions where managers have had higher and less sensitive to performance compensation prior to the crisis.
- (iv) Expected bailouts lead to higher risk-taking before the crisis and more failures occurring during the crisis.

5 Conclusion

This paper studies optimal incentive contracts in a setting with double moral hazard problem, in which an agent with limited liability privately chooses the riskiness of the project and can privately divert cash flows for consumption. Relative to the low risk project, the high risk project increases the probability of a high cash flow realization, but it also results in high losses in a bad state of nature, named “disaster”.

To avoid risk-taking and diverting funds, investors must cede additional rents to the manager. In the static setting, we find that the optimal contract that implements the low-risk regime and truthful reporting of cash flows may require a very high level of compensation for the manager if the contract terms are contingent only on the reported cash flows. The expected level of the managerial compensation can be much lower if disaster states can be identified ex-post by paying the manager a large bonus if the firm survives. It can be implemented by giving the agent out-of-money put options on the companies that are likely to be ruined in the disaster state.

In a dynamic context, because managerial rents must be reduced following poor performance to prevent fund diversion, poorly performing managers will take on disaster risk

even under an optimal contract. Even when disaster states can be identified ex-post, if performance is sufficiently weak the manager will forfeit eligibility for a bonus, and again take on disaster risk.

Our model can explain why suboptimal risk-taking can emerge even when investors are fully rational and managers are compensated optimally. Risk-taking is likely to take place when the disaster state is unlikely or after a history of poor performance, when the agent has little “skin” left in the game. As a result, the optimal contract has increased reliance on deferred compensation and provision of financial slack. Even absent evidence of risk-taking, small reductions in performance could lead to “harsh” punishments.

APPENDIX

A Proofs

A.1 Proof of Lemma B

Note that $W_t(\hat{Y}, q)$ is also the agent's promised value if $\hat{Y}_s$, $0 \leq s \leq t$, were the true cash flows and the agent reported truthfully. Therefore, without loss of generality we can prove (54) for the case in which the agent truthfully reports $\hat{Y} = Y$.¹³ In that case, by the law of iterated expectations

$$V_t = \int_0^t e^{-\gamma s} dI_s(Y) + e^{-\gamma t} W_t(Y, q), \quad (\text{A.1})$$

is a martingale and by the martingale representation theorem there is a processes β and ψ such that

$$dV_t = e^{-\gamma t} \beta_t(Y, q)(dY_t - (\mu_0 + \mu_1 q_t)dt) + e^{-\gamma t} \psi_t(Y, q)(dN_t - \delta dt) + (dR_t(Y, q) - E[dR_t(Y, q)]), \quad (\text{A.2})$$

where $dY_t - (\mu_0 + \mu_1 q_t)dt$ is a multiple of the standard Brownian motion for $t < \tau_L \wedge \tau_D$. If $dN_t=1$ and $q_t=1$, then $\psi_t = -W_t$, since the project liquidated immediately and the continuation payoff for the agent is zero. If $dN_t=1$ and $q_t=0$, then $\psi_t = 0$, since the contractual payments to the agent cannot be conditional on the disaster process realizations that do not lead to the disaster outcome. Thus,

$$\psi_t(Y, q) = -q_t W_t(Y, q). \quad (\text{A.3})$$

Differentiating (A.1) with respect to t we find

$$\begin{aligned} dV_t &= e^{-\gamma t} \beta_t(Y, q)(dY_t - (\mu_0 + \mu_1 q_t)dt) - e^{-\gamma t} q_t W_t(Y, q)(dN_t - \delta dt) + (dR_t(Y, q) - E[dR_t(Y, q)]) = \\ &e^{-\gamma t} dI_t(Y) - \gamma e^{-\gamma t} W_t(Y, q)dt + e^{-\gamma t} dW_t(Y, q), \end{aligned} \quad (\text{A.4})$$

and thus (54) holds. *QED*

A.2 Proof of Lemma C

If the agent truthfully reports the cash flows and chooses the equilibrium risk level q , then according (50) and (A.1) and Lemma B, his expected payoff is equal to

$$\begin{aligned} W_0 = E[V_\tau] &= E\left[V_0 + \int_0^\tau e^{-\gamma t} \beta_t(Y, q)(dY_t - (\mu_0 + \mu_1 q_t)dt) - \int_0^\tau e^{-\gamma t} q_t W_t(Y, q)(dN_t - \delta dt) + \int_0^\tau (dR_t - E[dR_t])\right] = \\ &E\left[V_0 + \int_0^\tau e^{-\gamma t} \beta_t(Y, q)(dY_t - (\mu_0 + \mu_1 q_t)dt)\right]. \end{aligned}$$

Let Y denote the cash flow corresponding to the equilibrium risk level q . If the agent reports $\hat{Y}_t$ and chooses risk level $\hat{q}_t$ at time t , he gains immediate income of $\lambda(dY_t + \mu_1(\hat{q}_t - q_t)dt - d\hat{Y}_t)$, while the contract assumes risk level q_t and treats the reported cash flow $\hat{Y}_t$ as the true cash flow. Since $E[dN_t] = \delta dt$, the agent's expected payoff under reporting strategy $\hat{Y}$ is given by

$$\begin{aligned} & E \left[V_0 + \int_0^\tau e^{-\gamma t} \beta_t(\hat{Y}, q) (d\hat{Y}_t - (\mu_0 + \mu_1 q_t)dt) + \lambda \int_0^\tau e^{-\gamma t} (dY_t + \mu_1(\hat{q}_t - q_t)dt - d\hat{Y}_t) - \int_0^\tau e^{-\gamma t} W_t (\hat{q}_t dN_t - q_t \delta dt) \right] = \\ & E \left[V_0 + \int_0^\tau e^{-\gamma t} \beta_t(\hat{Y}, q) (dY_t + \mu_1(\hat{q}_t - q_t)dt - (\mu_0 + \mu_1 q_t)dt) + \int_0^\tau e^{-\gamma t} (\lambda - \beta_t(\hat{Y}, q)) (dY_t + \mu_1(\hat{q}_t - q_t)dt - d\hat{Y}_t) \right] - \\ & E \left[\int_0^\tau e^{-\gamma t} \delta W_t (\hat{q}_t - q_t)dt \right] = \\ & W_0 + E \left[\int_0^\tau e^{-\gamma t} (\lambda - \beta_t(\hat{Y}, q)) (dY_t + \mu_1(\hat{q}_t - q_t)dt - d\hat{Y}_t) \right] + E \left[\int_0^\tau e^{-\gamma t} (\hat{q}_t - q_t) (\beta_t(\hat{Y}, q) \mu_1 - \delta W_t)dt \right]. \end{aligned}$$

We see from the first integral that if $\beta_t \geq \lambda$ for all t then the agent's payoff is maximized when the agent chooses $d\hat{Y}_t = dY_t + \mu_1(\hat{q}_t - q_t)dt$, since the agent cannot over-report cash flows. If $\beta_t < \lambda$ on a set of positive measure, then the agent is better off underreporting on this set than always telling the truth.

From the second integral, we can see that the high risk is optimal for the agent when $\beta_t(\hat{Y}, q) \mu_1 - \delta W > 0$, or $W_t < \beta_t(\hat{Y}, q) \frac{\mu_1}{\delta}$, and the low risk is optimal when $W_t \geq \beta_t(\hat{Y}, q) \frac{\mu_1}{\delta}$. QED

A.3 Proof of Proposition 5

Let us prove that b represents the principal's optimal profit, which is achieved by the contract outlined in the proposition. First, we note that b is strictly concave on $[0, W^p)$ and (W^s, W^c) , and affine on $[W^p, W^s]$ and $[W^c, \infty)$. We also note that because of the boundary conditions b is twice differentiable.

Define

$$G_t \equiv \int_0^t e^{-rs} (dY_s - dI_s) + e^{-rt} b(W_t). \quad (\text{A.5})$$

According to Lemmas B and C, under an arbitrary incentive compatible contract, W_t evolves according to

$$dW_t = (\gamma + \delta q_t) W_t dt - dI_t + \beta_t \sigma dZ_t - q_t W_t dN_t + (dR_t - E[dR_t]). \quad (\text{A.6})$$

Applying Ito's lemma gives

$$e^{rt} dG_t = \underbrace{\left(\mu_0 + \mu_1 q_t + (\gamma + \delta q_t) W_t b'(W_t) + \frac{1}{2} \beta_t^2 \sigma^2 b''(W_t) - r b(W_t) + \delta q_t (L - M - b(W_t)) \right)}_{\leq 0} dt \\ - \underbrace{(1 + b'(W_t)) dI_t}_{\leq 0} + (1 + \beta_t b'(W_t)) \sigma dZ_t + \underbrace{\left(b(W_t + J_t^R) - b(W_t) - b'(W_t) J_t^R \right)}_{\leq 0} d\Delta_t^R. \quad (\text{A.7})$$

From (67)-(69) and the facts that $b(W_t)$ is weakly concave and $b'(W_t) \geq -1$, G_t is a supermartingale. It is a martingale if and only if $\beta_t = \lambda$, $W_t \leq W^C$ for $t > 0$, I_t is increasing only when $W_t \geq W^C$, and jumps of the size $J = W^S - W^P$ can only happen when W_t reaches thresholds W^P or W^S . Indeed, since b is strictly concave on $[W^0, W^P)$ and $[W^S, W^C)$, any jump outside interval $[W^P, W^S]$ makes the last term negative. On the other hand, one can show that the first term is negative when $W_t \in (W^P, W^S)$, or $W_t > W^C$.

We can now evaluate the principal's payoff for an arbitrary incentive compatible contract. Note that $b(W_\tau) = L - M 1_{\tau_D \leq \tau_L}$. For all $t < \infty$,

$$E \left[\int_0^\tau e^{-rs} (dY_s - dI_s) + e^{-r\tau} (L 1_{\tau_L < \tau_D} + (L - M) 1_{\tau_D \leq \tau_L}) \right] \\ = E \left[G_{t \wedge \tau} + 1_{t \leq \tau} \left(\int_t^\tau e^{-rs} (dY_s - dI_s) + e^{-r\tau} (L 1_{\tau_L < \tau_D} + (L - M) 1_{\tau_D \leq \tau_L}) - e^{-rt} b(W_t) \right) \right] \\ = \underbrace{E[G_{t \wedge \tau}]}_{\leq G_0 = b(W_0)} + e^{-rt} E \left[1_{t \leq \tau} \left(\underbrace{E_t \left[\int_t^\tau e^{-r(s-t)} (dY_s - dI_s) + e^{-r(\tau-t)} (L 1_{\tau_L < \tau_D} + (L - M) 1_{\tau_D \leq \tau_L}) \right]}_{\leq \mu_0/r - W_t = \text{first best}} - b(W_t) \right) \right].$$

Now, since $b'(W) \geq -1$, $\mu_0/r - W - b(W) \leq \mu_0/r - L$. Therefore, letting $t \rightarrow \infty$,

$$E \left[\int_0^\tau e^{-rs} (dY_s - dI_s) + e^{-r\tau} (L 1_{\tau_L < \tau_D} + (L - M) 1_{\tau_D \leq \tau_L}) \right] \leq b(W_0). \quad (\text{A.8})$$

Finally, for a contract that satisfies the conditions of the proposition, G_t is a martingale until time τ because $b(W_t)$ stays bounded. Therefore, the payoff $b(W_0)$ is achieved with equality. *QED*

A.4 Proof of Lemma E

If the agent truthfully reports the cash flows and chooses the equilibrium risk level q , then according to relations (50), (A.1) and Lemma D, his expected payoff is equal to

$$W_0 = E[V_\tau] = E\left[V_0 + \int_0^\tau e^{-\gamma t} \beta_t(Y, q)(dY_t - (\mu_0 + \mu_1 q_t)dt) + \int_0^\tau e^{-\gamma t} ((1 - q_t)B_t(Y, q) - q_t W_t)(dN_t - \delta dt)\right] = \\ E\left[V_0 + \int_0^\tau e^{-\gamma t} \beta_t(Y, q)(dY_t - (\mu_0 + \mu_1 q_t)dt)\right].$$

Let Y denote the cash flow corresponding to the equilibrium risk level q . If the agent reports $\hat{Y}_t$ and chooses risk level $\hat{q}_t$ at time t , he gains immediate income of $\lambda(dY_t + \mu_1(\hat{q}_t - q_t)dt - d\hat{Y}_t)$, while the contract assumes risk level q_t and treats the reported cash flow $\hat{Y}$ as the true cash flow. Since $E[dN_t] = \delta dt$, the agent's expected payoff under reporting strategy $\hat{Y}$ is given by

$$E\left[V_0 + \int_0^\tau e^{-\gamma t} \beta_t(\hat{Y}, q)(d\hat{Y}_t - (\mu_0 + \mu_1 q_t)dt) + \lambda \int_0^\tau e^{-\gamma t} (dY_t + \mu_1(\hat{q}_t - q_t)dt - d\hat{Y}_t)\right] + \\ E\left[\int_0^\tau e^{-\gamma t} \left((1 - \hat{q}_t)B_t(\hat{Y}, q) - \hat{q}_t W_t - ((1 - q_t)B_t(\hat{Y}, q) - q_t W_t)\delta dt\right)\right] = \\ E\left[V_0 + \int_0^\tau e^{-\gamma t} \beta_t(\hat{Y}, q)(dY_t + \mu_1(\hat{q}_t - q_t)dt - (\mu_0 + \mu_1 q_t)dt) + \int_0^\tau e^{-\gamma t} (\lambda - \beta_t(\hat{Y}, q))(dY_t + \mu_1(\hat{q}_t - q_t)dt - d\hat{Y}_t)\right] - \\ E\left[\int_0^\tau e^{-\gamma t} (\hat{q}_t - q_t)(W_t + B_t(\hat{Y}, q))\delta dt\right] = \\ W_0 + E\left[\int_0^\tau e^{-\gamma t} (\lambda - \beta_t(\hat{Y}, q))(dY_t + \mu_1(\hat{q}_t - q_t)dt - d\hat{Y}_t)\right] + E\left[\int_0^\tau e^{-\gamma t} (\hat{q}_t - q_t)(\beta_t(\hat{Y}, q)\mu_1 - \delta(W_t + B_t(\hat{Y}, q)))dt\right].$$

We see from the first integral that if $\beta_t \geq \lambda$ for all t then the agent's payoff is maximized when the agent chooses $d\hat{Y}_t = dY_t + \mu_1(\hat{q}_t - q_t)dt$, since the agent cannot over-report cash flows. If $\beta_t < \lambda$ on a set of positive measure, then the agent is better off underreporting on this set than always telling the truth.

It directly follows from the second integral that the high risk is optimal for the agent either when $\beta_t(\hat{Y}, q)\mu_1 - \delta(W_t + B_t(\hat{Y}, q)) > 0$, or when $W_t + B_t(\hat{Y}, q) < \beta_t(\hat{Y}, q)\frac{\mu_1}{\delta}$, and that the low risk is optimal when $W_t + B_t(\hat{Y}, q) \geq \beta_t(\hat{Y}, q)\frac{\mu_1}{\delta}$. QED

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Figure 1. Illustration of the proof of Proposition 1. The IC constraint is satisfied everywhere above the 45-degree straight line starting at λ . The low-risk taking constraint is satisfied below a straight line starting at zero. Both constraints are simultaneously satisfied everywhere between the two lines to the right of their intersection shown by a thick dot. The dotted line represents "promise keeping" constraint where it goes through the cheapest contract.

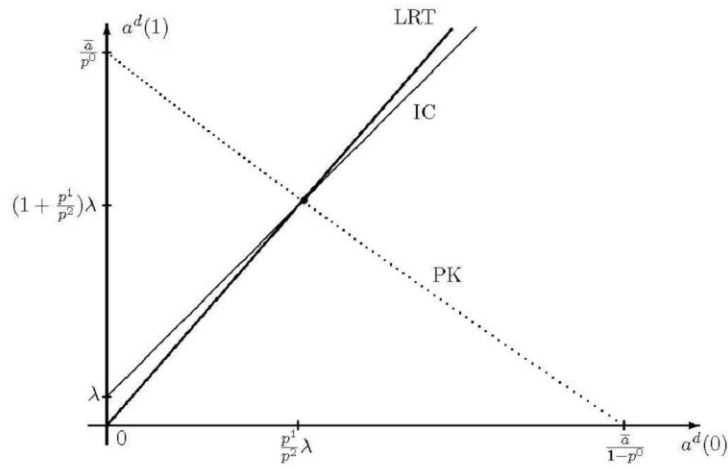


Figure 2. Illustration of the intuition behind the optimal contract with risk-taking. The IC constraint is satisfied everywhere above the 45-degree straight line starting at λ . The dotted line represents "promise keeping" constraint where it goes through the cheapest contract shown by $(0, \lambda)$.

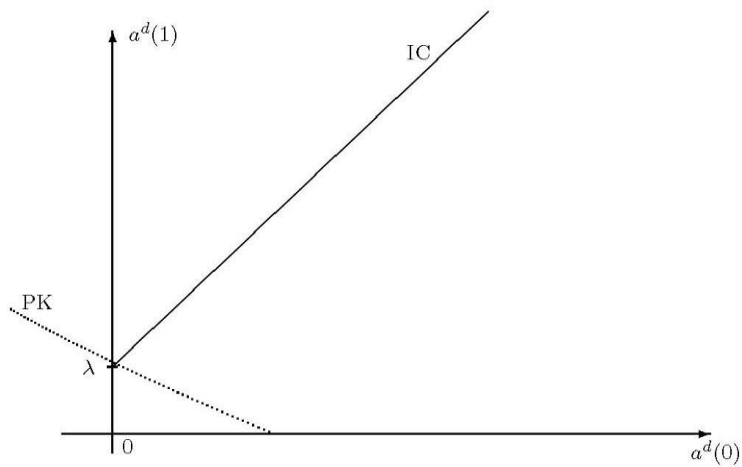


Figure 3. Illustration of the solution to the model where conditioning on the state of nature is allowed. The IC constraint is satisfied everywhere above the 45-degree straight line starting at $(p^2/p^1)a^d(0,D)$. Both constraints can be simultaneously satisfied only if LRT constraint is shifted above the IC constraint. The cheapest incentive compatible contract is achieved when IC and LRT coincide and the PK constraint goes through $(0,\lambda)$ point.

